Motor Fusing System



Full automation motor fusing system from loading motors to unloading after fusing.

Features

This is a fully automated motor fusing system from loading motors to unloading after fusing.

- Fully automated from loading motors to unloading after fusing.
- Force and penetration can be controlled for stable fusing.
- Process conditions such as current, voltage, fusing time, force, and penetration, of each segment can be saved.

Specifications

Motor size	Core diameter should be Φ30mm or bigger.
Takt time	78 sec. (In case of 30 segments)
Workpiece conveying method	Robot
Dimensions	1000W x 700D x 1600H mm

